SMITHSONIAN TETHERED EXO-MARINER

REMOTELY OPERATED VECHICLE



AWARD WINNING



Smithsonian Intern TEAM

Emma Bennett, CEO, Chief Design ENG. Hours 11th Grade 17 MAST Academy 3rd year MATE 140 Kendal Lee - Mission Specialist, Engineer 11th Grade !7. John Carrol Catholic HS, 3rd year MATE Barry Smith, Safety Captain ,co-Pilot 11th Grade 17 Lincoln Park Academy 3rd year MATE 130 Nicholas Stange, Engineer, Technician 10th Grade 16 MOA-Westwood HS 2nd year MATE Total hours Woody Lee, Mentor and Captain Smithsonian Marine Lab, 600 **Research Specialist** 3rd year MATE

STEM ROV Company Spec Sheet

Size : 35cm35cm x33cm x4cm

Weight:~11kg

Special Features

- Dual cameras; Composite and HD low light video and stills
- Modular Design
- Light Weight High Strength Aluminum Chassis
- Adjustable Manipulator
- Sensors– Pressure Depth Gauge
- Switch Regulators High Efficiency Step Down/Up
- On Board Telemetry: Six Axis Gyroscope , Compass
- Drone Technology /ArduSub Software Works QGround Control
- Pressure Release Valve For Testing WPC
- T100/T200 Blue Robotics Thrusters For Heavy Lift
- Xbox Control Bluetooth
- Changeable Platform Configurations
- Neutrally Buoyant Flexible Kevlar Strength Tether

Safety :

- Thermoplastic Penetrators and Skid Custom Guards
- Motor Guards with high visibly marks / Impact resistant tether
 - Cost: \$1762.00



Smithsonian Marine Station, Ft Pierce , Florida MATE International Competition 3200 miles